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Statistics Applied to Economics  
Degree in Economics

F.Tusell

Dpto. Economía Aplicada III (Estadística y Econometría)

Curso 2011–2012



Universidad del País Vasco    Euskal Herriko Unibertsitatea

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Índice I

- Consistency
- Efficiency
- Suficiency

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Consistency (I) (reminder: probability limits)

- ▶ We say that the limit in probability of a sequence or random variables  $\{Z_n\}$  is  $Z$  if for any  $\epsilon > 0, \eta > 0$  there is  $N$  such that for  $n > N$ :

$$P(|Z_n - Z| < \epsilon) \geq 1 - \eta$$

- ▶ In plain English: if taking sufficiently advanced terms of  $\{Z_n\}$  we can be within  $\epsilon$  of  $Z$  with probability as close to 1 as we wish.
- ▶ Compare with usual notion of limit in mathematical analysis.
- ▶ Usual notation is  $Z_n \xrightarrow{p} Z$  or  $\text{plim}(Z_n) = Z$ .

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## Consistency (II)

- ▶  $\hat{\theta}_n$  denotes an estimator of  $\theta$  based on a sample of size  $n$ . For instance, we might have

$$\hat{\theta}_n = \frac{X_1 + X_2 + \dots + X_n}{n}$$

- ▶  $\hat{\theta}_n$  is consistent if  $\hat{\theta}_n \xrightarrow{P} \theta$
- ▶ In plain English: if by increasing the sample size we can obtain arbitrary precision with as close to 1 confidence as we choose.
- ▶ In general, consistency is the very least we ask for. (We want to be rewarded for our effort in sampling!)

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## Consistency (III)

- ▶ We can usually show consistency by using; i) The laws of large numbers, or ii) Tchebycheb inequality, among other ways.
- ▶ Consistency does not imply unbiasedness.

How can we have consistency and not unbiasedness?

Think of  $\hat{\theta}_n$  taking the true value  $\theta$  with probability  $1 - \frac{1}{n}$  and the value  $n$  with probability  $\frac{1}{n}$ .

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## Consistency via Tchebychev inequality

**Example:** consistency of  $\hat{\lambda} = \bar{X}$  as estimator of  $\lambda$  of a  $\mathcal{P}(\lambda)$ .

- ▶ We know  $E[\hat{\lambda}] = \lambda$  and  $\text{Var}(\hat{\lambda}) = \lambda/n$ .
- ▶ Then (Tchebycheff),

$$P(|\hat{\lambda} - \lambda| < \underbrace{k\sqrt{\lambda/n}}_{\epsilon}) \geq \underbrace{1 - 1/k^2}_{1-\eta}$$

- ▶ Make your pick of  $1 - \eta$  as close to 1 as desired; whatever the implied  $k$ , we only have to choose  $n$  large enough to make  $\epsilon$  as small as we wish.

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## Unbiasedness + variance $\rightarrow 0 \implies$ consistency

- ▶ Again, simple application of Tchebychev's inequality.
- ▶ Unbiasedness implies  $E(\hat{\theta}_n) = \theta$ .

$$P(|\hat{\theta}_n - \theta| < \underbrace{k\sigma_n}_{\epsilon}) \geq \underbrace{1 - 1/k^2}_{1-\eta}$$

- ▶ Let  $1 - \eta$  be as close to 1 as desired; whatever the implied  $k$ ,  $\epsilon$  can be made small for large  $n$ , as  $\sigma_n \rightarrow 0$ .
- ▶ If both variance and bias decrease to zero, we also have consistency.

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## Consistency of moment estimators

- ▶ Moment estimators are usually consistent.
- ▶ Sketch of argument for a particular case:

$$m = \alpha_1(\hat{\theta}) = \bar{X}$$

- ▶ If  $\alpha_1(\hat{\theta})$  has a continuous inverse function,  $\hat{\theta} = \alpha_1^{-1}(\bar{X})$ .
- ▶ Now, convergence of  $\bar{X}$  to  $m$  (law of large numbers) entails convergence of  $\hat{\theta}$  to  $\theta$ :

$$\text{plim}(\hat{\theta}) = \alpha_1^{-1}(\text{plim}(\bar{X})) = \alpha_1^{-1}(m) = \theta$$

- ▶ Notice: if  $\alpha_q^{-1}(\cdot)$  were not continuous,  $\bar{X}$  could be very close of  $m$  and  $\alpha_q^{-1}(\bar{X})$  **not** close to  $\alpha_q^{-1}(m) = \theta$ .

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## Consistency is not everything!

- ▶ Consistency is an asymptotic property. It tells us what happen when the sample size goes to infinity.
- ▶ In practice, we may be limited to small samples, and then the consistency property offers little confort.
- ▶ Example: (artificial). In a  $\mathcal{P}(\lambda)$ ,

$$\hat{\lambda}_n = \begin{cases} 0 & \text{if } n < 10^5. \\ \bar{X} & \text{if } n \geq 10^5. \end{cases}$$

would be consistent (but pretty bad for sample sizes  $n$  below  $10^5$ !).

- ▶ Consistency is reassuring, but we need to check for realistic sample sizes (often through simulation).

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## Efficiency

- ▶ Among estimators which are both unbiased, it makes sense to chose the one with smallest variance.
- ▶ For  $\hat{\theta}_1$  and  $\hat{\theta}_2$  both unbiased estimators of  $\theta$ , we define *efficiency of  $\hat{\theta}_1$  relative to  $\hat{\theta}_2$*  as:

$$\frac{\text{Var}(\hat{\theta}_2)}{\text{Var}(\hat{\theta}_1)}$$

- ▶ Assume  $\text{Var}(\hat{\theta}_1)$  were the lowest attainable. Then, any estimator with efficiency 1 relative to  $\hat{\theta}_1$  will be called **efficient**.
- ▶ But, how do we find a  $\hat{\theta}_1$  which cannot be improved upon?

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## The Cramer-Rao bound

- ▶ It turns out that we do have a universal yardstick, under *regularity* conditions (more on that later)
- ▶ For any unbiased  $\hat{\theta}$  based on  $n$  observations under regularity conditions:

$$\text{Var}(\hat{\theta}) \geq \frac{1}{nI(\theta)}$$

this is the celebrated Cramer-Rao lower bound.

- ▶  $I(\theta)$  is the so-called Fisher information contained in one observation, and is defined as:

$$I(\theta) = E \left( \frac{\partial \log f(x; \theta)}{\partial \theta} \right)^2$$

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## Intuition for Fisher information

- ▶ Why is  $I(\theta)$  a measure of information?
- ▶ Imagine a given (fixed)  $x$ ;

$$\left(\frac{\partial \log f(x; \theta)}{\partial \theta}\right)^2$$

measures how fast  $\log f(x; \theta)$  changes in response to changes in  $\theta$ .

- ▶ If  $\log f(x; \theta)$  were very flat, close values of  $\theta$  would have similar likelihood, and we would be very uncertain about the "true"  $\theta$ .
- ▶ If  $\log f(x; \theta)$  changes fast, it gives much information about  $\theta$ .
- ▶ If we average the derivative over possible values of  $X$  we have Fisher information.

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## Efficient estimators and the Cramer-Rao bound

- ▶ Under regularity conditions, if

$$\text{Var}(\hat{\theta}) = \frac{1}{nI(\theta)}$$

the Cramer-Rao lower bound implies the unbiased  $\hat{\theta}$  cannot be improved upon by any other unbiased estimator. It is then called **efficient**.

- ▶ We *know* what the optimum is before we start.
- ▶ No fear that there is a better estimator that just didn't occur to us!

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## The Cramer-Rao bound: historical notes

- ▶ Harald Cramér (1892-1985), Swedish statistician, author of the extremely influential *Mathematical Methods of Statistics* (1946), still a good reading.
- ▶ C.R.Rao (1920-), a distinguished Indian statistician. Aside from the Cramer-Rao bound, other contributions like the celebrated Rao-Blackwell theorem (in the same vein than the Cramer-Rao bound, but more powerful).
- ▶ The original publications date of 1945 (Rao) and 1946 (Cramer).

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## What are those regularity conditions?

- ▶ Basically,
  1. The support of the distribution does not depend on the parameter. Example of violation:  $U(0, \theta)$ .
  2. The log likelihood function "sufficiently smooth": differentiable and order of integration and differentiation interchangeable:

$$\frac{\partial}{\partial \theta} E(\log f(x, \theta)) = E\left(\frac{\partial \log f(x, \theta)}{\partial \theta}\right)$$

- ▶ Failure of these conditions render unusable the Cramer-Rao bound.

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## A trick to compute the Cramer-Rao bound.

- ▶ It turns out that

$$E\left(\frac{\partial \log f(X, \theta)}{\partial \theta}\right)^2 = -E\left(\frac{\partial^2 \log f(X, \theta)}{\partial \theta^2}\right)$$

- ▶ Either expression can be used to compute Fisher's information (the denominator of the Cramer-Rao bound).
- ▶ Usually best the second derivative, but sometimes looking at the first we can easily compute its mean value.

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## The Cramer-Rao bound: examples (I)

We know  $\bar{X}$  is unbiased for  $\lambda$  in a  $\mathcal{P}(\lambda)$ . Its variance is  $\lambda/n$ . Is there anything better?

$$\begin{aligned}\log f(X, \lambda) &= -\lambda + X \log(\lambda) - \log(X!) \\ \frac{\partial \log f(X, \lambda)}{\partial \lambda} &= -1 + X/\lambda = \left(\frac{X - \lambda}{\lambda}\right) \\ E\left(\frac{X - \lambda}{\lambda}\right)^2 &= \frac{1}{\lambda}\end{aligned}$$

The Cramer-Rao is

$$\text{Var}(\hat{\lambda}) \geq \frac{1}{n \frac{1}{\lambda}} = \frac{\lambda}{n}$$

so  $\bar{X}$  is optimal in the unbiased class.

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## The Cramer-Rao bound: examples (II)

- ▶ We might have missed the fact that:

$$E\left(\frac{X - \lambda}{\lambda}\right)^2 = \frac{1}{\lambda};$$

- ▶ In that case, taking the second derivative of

$$\left(\frac{X - \lambda}{\lambda}\right)$$

would have readily given us  $1/\lambda$ .

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## The Cramer-Rao bound: examples (III)

- ▶ Consider estimation of  $p$  in a binary distribution.
- ▶ Moment and MLE is  $\hat{p} = \bar{X}$  with variance  $p(1-p)/n$ .
- ▶ We have,

$$\begin{aligned}\log f(X, p) &= X \log(p) + (1 - X) \log(1 - p) \\ \frac{\partial \log f(X, p)}{\partial p} &= \frac{X}{p} - \frac{1 - X}{1 - p} \\ E\left(\frac{X}{p} - \frac{1 - X}{1 - p}\right)^2 &= E\left(\frac{X - p}{p(1 - p)}\right)^2 = \frac{1}{p(1 - p)}\end{aligned}$$

- ▶ The CR bound is then,

$$\text{Var}(\hat{p}) \geq \frac{1}{n \frac{1}{p(1-p)}} = \frac{p(1-p)}{n}$$

and  $\hat{p} = \bar{X}$  is efficient.

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## Some facts about the Cramer-Rao bound

- ▶ The CR bound may not be attainable.
- ▶ What it says is that we can do no better. . .
- ▶ . . .not that we can do as well.
- ▶ Hence, estimators with efficiency 1 as defined previously, may not exist.
- ▶ In general, the MLE reaches the CR lower bound, at least asymptotically.

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## The concept of sufficiency (I)

- ▶ To obtain estimators, we have made use of a *statistic*, a function of the sample.
- ▶ Are we losing something?
- ▶ Or, could we do better looking individually at each sample value, rather than to a summarizing function?
- ▶ Loose idea: when a statistic “squeezes all the juice” out of a sample, it is sufficient.
- ▶ We have to formalize this “squeezing” property.

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## The concept of sufficiency (II)

- ▶ If given a statistic  $S = S(\vec{X})$  the conditional density (or probability)

$$f(\vec{X}|S) = \frac{f_{\vec{X}}(\vec{X}; \theta)}{f_S(S; \theta)}$$

is independent of  $\theta$ ,  $S(\vec{X})$  is said to be **sufficient** for  $\theta$ .

- ▶ Motivation: if once we know  $S = S(\vec{X})$  the density (or probability) of the sample values does not depend on  $\theta$ , *knowing those individual sample values cannot be of help in determining  $\theta$* .
- ▶ All information about  $\theta$  is then contained in  $S = S(\vec{X})$ .

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## The concept of sufficiency (III)

- ▶ Let  $X_1, \dots, X_n \sim \mathcal{P}(\lambda)$ . Let  $S = X_1 + \dots + X_n$ . We know  $S \sim \mathcal{P}(n\lambda)$ . Then

$$\begin{aligned} f(\vec{X}|S) &= \frac{f_{\vec{X}}(\vec{X}; \lambda)}{f_S(S; \lambda)} \\ &= \frac{\prod_{i=1}^n e^{-\lambda} \lambda^{X_i} / X_i!}{e^{-n\lambda} (n\lambda)^S / S!} \\ &= \frac{S!}{X_1! X_2! \dots X_n!} \lambda^{-S} \end{aligned}$$

- ▶ Therefore,  $S$  (or any other 1-1 function of  $S$ ) is sufficient for  $\lambda$ .

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## The concept of sufficiency (IV)

- ▶ As a further example, let's consider the ordered sample  $X_{(1)}, \dots, X_{(n)}$ .
- ▶ If sampled values are i.i.d., values may arise in any order.
- ▶ Given  $X_{(1)}, \dots, X_{(n)}$ , any order is equally likely, with probability  $1/n!$ , whichever the parameter(s) of the distribution may be.
- ▶ Therefore,  $X_{(1)}, \dots, X_{(n)}$  is always a sufficient statistic, although of little interest (it doesn't "compact" information).

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## The factorization theorem (I)

- ▶ If we can decompose the joint density (or probability) as a product,

$$f_{\vec{X}}(\vec{X}; \theta) = g(S(\vec{X}); \theta) \times h(\vec{X})$$

where  $h(\vec{X})$  does **not** depend on  $\theta$ , then  $S$  is sufficient.

- ▶ Quite easy to prove.
- ▶ Quite practical; we only have to see which function (or functions) of the sample "carry with them" the parameter  $\theta$ .

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## The factorization theorem (II)

- ▶ Take the Poisson case again. We have,

$$\begin{aligned} f_{\vec{X}}(\vec{X}; \lambda) &= \prod_{i=1}^n e^{-\lambda} \lambda^{X_i} / X_i! \\ &= \underbrace{e^{-n\lambda} \lambda^{X_1 + \dots + X_n}}_{g(S, \lambda)} \times \underbrace{\prod_{i=1}^n (1/X_i!)}_{h(\vec{X})} \end{aligned}$$

- ▶ Clearly,  $S = X_1 + \dots + X_n$  is sufficient.

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## The factorization theorem (III)

- ▶ MLE have "built in" sufficiency.
- ▶ Using the factorization theorem, to maximize the left hand side of

$$f_{\vec{X}}(\vec{X}; \theta) = g(S(\vec{X}); \theta) \times h(\vec{X})$$

as a function of  $\theta$ , we only need  $g(S(\vec{X}); \theta)$ ;

- ▶ The term  $h(\vec{X})$  is just a constant in the likelihood function.

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## Some ill-behaved distributions

- ▶ Most distributions in common use have sufficient statistics for their parameters.
- ▶ This is not always the case. Consider the Cauchy distribution (aka  $t_1$ ) with location  $\theta$ :

$$f_X(x : \theta) = \frac{1}{\pi} \frac{1}{1 + (x - \theta)^2}$$

- ▶ If you use the factorization theorem to look for sufficient statistics,

$$f_{\vec{X}}(\vec{X} : \theta) = g(S(\vec{X}); \theta) \times h(\vec{X})$$

hard as you may try, you will at least need the ordered sample (which is always a sufficient statistic).

- ▶ No further reduction is possible.

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